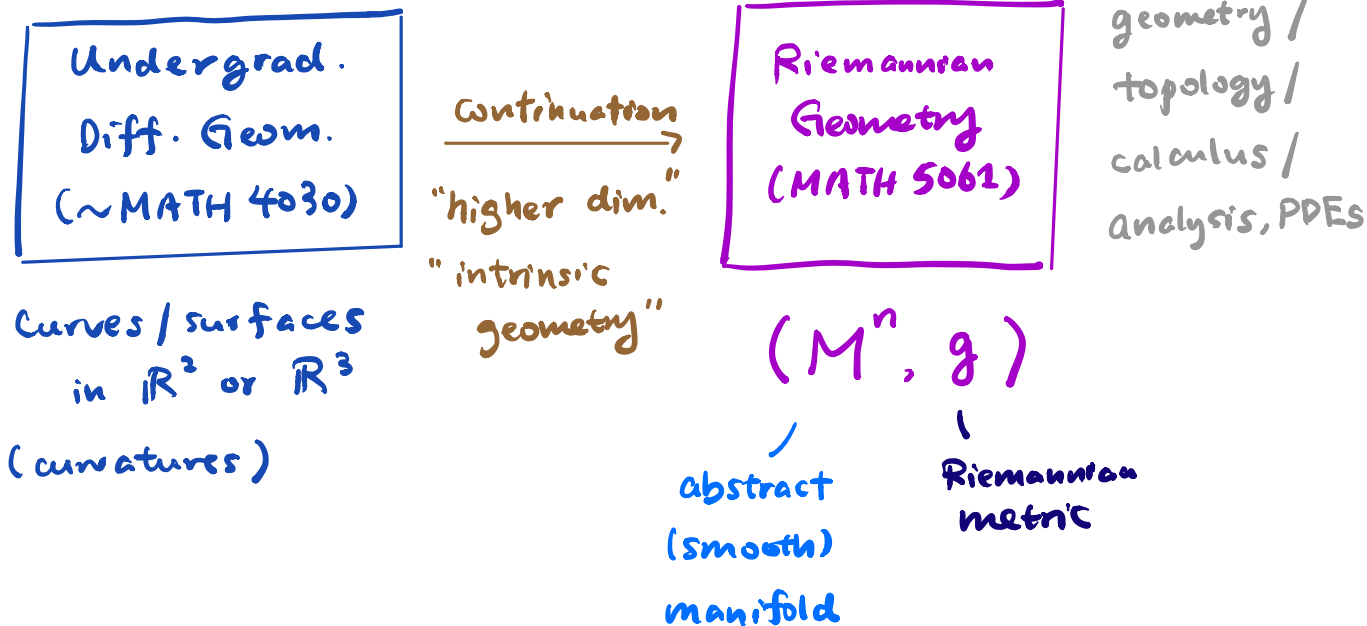


MATH 5061 Riemannian Geometry I

Q: What is "Riemannian Geometry"?



We begin with the theory of (smooth C^∞) manifolds.

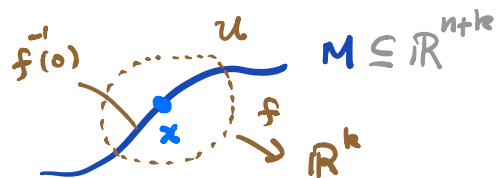
(Ref: F. Warner "Foundations of Differential Manifolds and Lie Groups"
J. Lee "Introduction to Smooth Manifolds")

§ Submanifolds of \mathbb{R}^N

Defⁿ: $M \subseteq \mathbb{R}^{n+k}$ is an n -dim'l submanifold of \mathbb{R}^{n+k}

(of class C^p) if $\forall x \in M, \exists$ nbd. $x \in U \subseteq \mathbb{R}^{n+k}$ and

a C^p -map $f: U \rightarrow \mathbb{R}^k$ s.t.



(i) $df_x: \mathbb{R}^{n+k} \rightarrow \mathbb{R}^k$ is onto $\forall x \in U$ (i.e. f is a submersion)

(ii) $U \cap M = f^{-1}(0)$

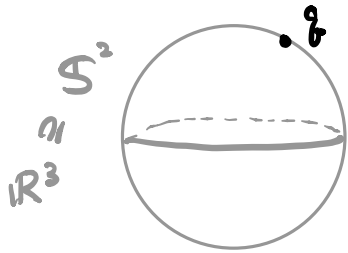
Idea: $M \stackrel{\text{locally}}{=} \text{"regular" zero set of a } C^p \text{ (vector-valued) function}$

Here, $k = \text{codim } M$, $n = \text{dim } M$.

When $k = 1$, we say M is a **hypersurface**.

Examples of submfd in \mathbb{R}^n

(a) Sphere $S^n := \{ (x_0, \dots, x_n) \in \mathbb{R}^{n+1} \mid x_0^2 + \dots + x_n^2 = 1 \}$



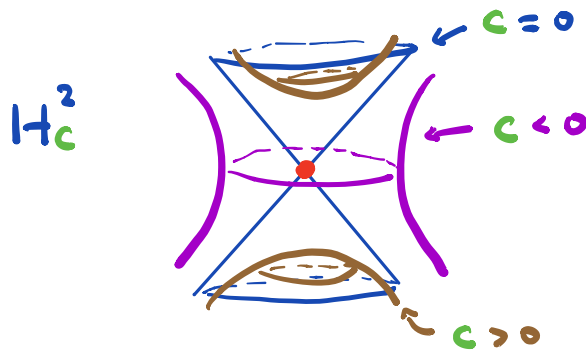
$$f(x, y, z) = x^2 + y^2 + z^2 - 1$$

$$\Rightarrow f: \mathbb{R}^3 \rightarrow \mathbb{R} \quad C^\infty \text{ and } f^{-1}(0) = S^2$$

$$df_q = (2x, 2y, 2z) \neq 0 \quad \forall q \in S^2$$

(b) Hyperboloid $H_c^n := \{ (x_0, \dots, x_n) \in \mathbb{R}^{n+1} \mid x_0^2 - x_1^2 - \dots - x_n^2 = c \}$
 is a C^∞ -submfd in \mathbb{R}^{n+1} when $0 \neq c \in \mathbb{R}$.

$n=2$:



(c) Torus $T^n := \{ (z_1, \dots, z_n) \in \mathbb{C}^n \mid |z_1|^2 + \dots + |z_n|^2 = 1 \}$

is a C^∞ -submanifold of $\mathbb{C}^n \cong \mathbb{R}^{2n}$

($\text{dim} = n$, $\text{codim} = n$)

(d) $SO(n) := \{ A \in M_n(\mathbb{R}) \mid A^t A = I, \det A = 1 \}$

is a C^∞ -submfd of $M_n(\mathbb{R}) \cong \mathbb{R}^{n^2}$ ($\text{dim } SO(n) = \frac{n(n-1)}{2}$)

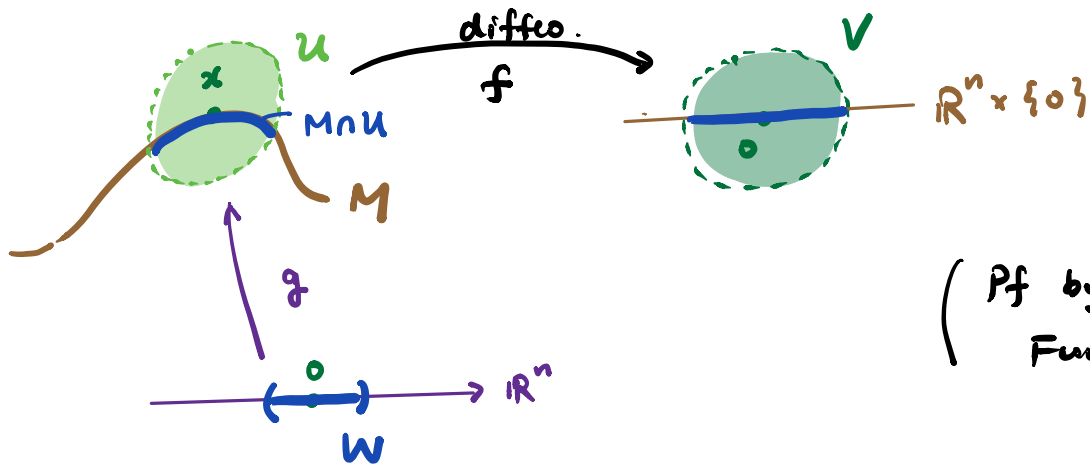
Prop: TFAE:

(i) $M^n \subseteq \mathbb{R}^{n+k}$ is a C^p -submanifold

(ii) $\forall x \in M, \exists \text{ nbd } x \in U \subseteq \mathbb{R}^{n+k}, 0 \in V \subseteq \mathbb{R}^{n+k}$

and a C^p -diffeomorphism $f: U \rightarrow V$

s.t. $f(U \cap M) = V \cap (\mathbb{R}^n \times \{0\})$



(iii) $\forall x \in M, \exists \text{ nbd } x \in U \subseteq \mathbb{R}^{n+k}$ and $0 \in W \subseteq \mathbb{R}^n$

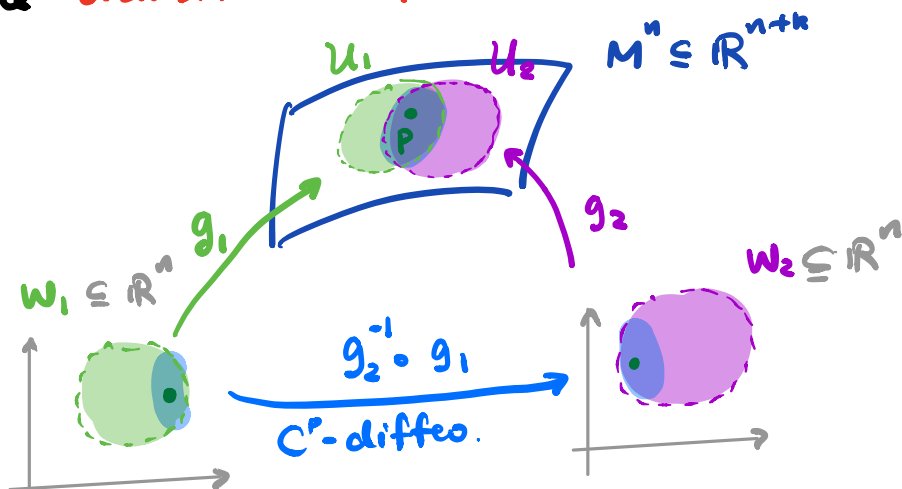
and a C^p -map $g: W \rightarrow \mathbb{R}^{n+k}$

s.t. g is a homeomorphism onto its image $g(W) = M \cap U$

with dg_0 is 1-1. ("local parametrization / chart")

Remark: For any two such charts $g_i: W_i \rightarrow \mathbb{R}^{n+k}, i=1,2$, as in (iii)

then the **transition maps** $g_2^{-1} \circ g_1$ is a C^p -diffeomorphism



§ Abstract Manifolds

Idea: " n -manifolds" $\stackrel{\text{"locally"}}{\cong}$ open subsets of \mathbb{R}^n
described by "compatible" charts into \mathbb{R}^n

ASSUMÉ: M Hausdorff, "paracompact" topological space

[$\Rightarrow \exists$ "partition of unity"]

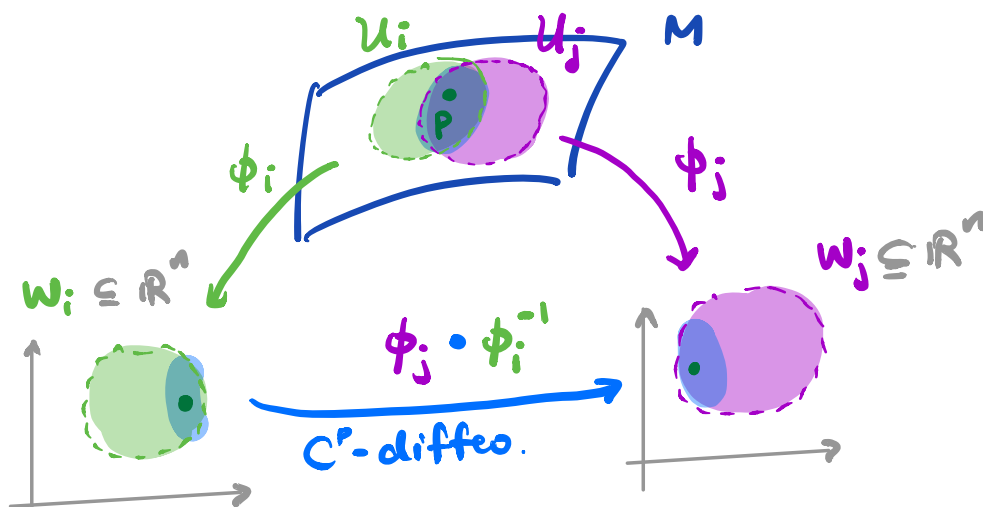
Defⁿ: A C^p -atlas on M is a collection of charts $\{(U_i, \phi_i)\}_{i \in I}$

s.t. (i) $\{U_i\}_{i \in I}$ forms an open cover of M

(ii) $\phi_i : U_i \rightarrow W_i \subseteq \mathbb{R}^n$ are homeomorphisms $\forall i \in I$

and the transition maps

$\phi_j \circ \phi_i^{-1} : \phi_i(U_i \cap U_j) \rightarrow \phi_j(U_i \cap U_j)$ are C^p -diffeo.



Defⁿ: $\{(U_i, \phi_i)\}_{i \in I} \sim \{(V_j, \psi_j)\}_{j \in J}$ if their union is an atlas

Def²: An equivalence class of C^p -atlas on M is called a **differentiable structure** (of class C^p) on M

A **differential manifold** consists of a Hausdorff, paracompact topological space M together with an atlas $\{(U_i, \phi_i)\}_{i \in I}$.

Remark: M connected $\Rightarrow \dim M = n$ well-defined
(by "invariance of domain")

ASSUME: M^n connected, smooth (i.e. C^∞) manifold

Def²: $N \subseteq M^n$ is a **submanifold** if $\forall p \in N, \exists$ chart (U, ϕ) of M s.t. $p \in U$ and $\phi(N \cap U) \subseteq \mathbb{R}^n$ is a submfld.

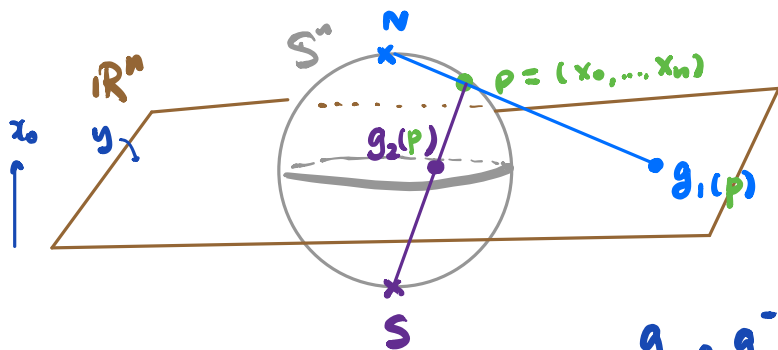
Examples of abstract manifolds

(a) submflds of \mathbb{R}^{n+k}

(b) $\exists C^\infty$ -structure on a square (not inherited from \mathbb{R}^2)



(c) $S^n \subseteq \mathbb{R}^{n+1}$ can be covered by only two charts:



$$g_1(x_0, \dots, x_n) = \frac{(x_1, \dots, x_n)}{1 - x_0} \quad p \neq N$$

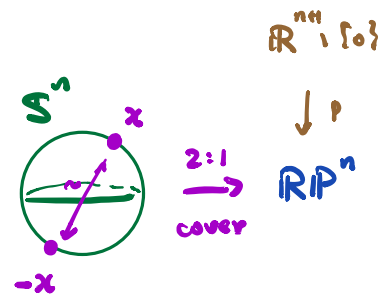
$$g_2(x_0, \dots, x_n) = \frac{(x_1, \dots, x_n)}{1 + x_0} \quad p \neq S$$

$$g_2 \circ g_1^{-1}(y) = \frac{y}{\|y\|^2} \quad \text{diffeo. on } \mathbb{R}^n \setminus \{0\}.$$

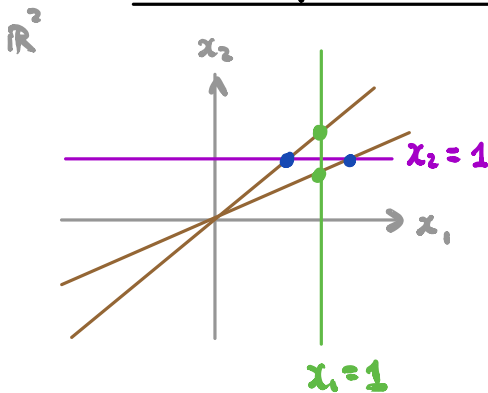
(d) Real Projective Space $\mathbb{R}P^n$.

$$\mathbb{R}P^n := \mathbb{R}^{n+1} \setminus \{0\} / \sim \quad = \mathbb{S}^n / \{\pm 1\}$$

$x \sim \lambda x$
($\lambda \neq 0$)



A description of C^∞ -structure on $\mathbb{R}P^n$:



$$\begin{aligned} \Phi_1: \{x_1 \neq 0\} &\rightarrow \mathbb{R} & \Phi_1(x_1, x_2) &= \frac{x_2}{x_1} \\ \Phi_2: \{x_2 \neq 0\} &\rightarrow \mathbb{R} & \Phi_2(x_1, x_2) &= \frac{x_1}{x_2} \end{aligned}$$

Note: $\Phi_i(\lambda x_1, \lambda x_2) = \Phi_i(x_1, x_2)$ ($\lambda \neq 0$)

$\leadsto \Phi_i$ are well-defined on $\mathbb{R}P^1$.

and they form a chart on $\mathbb{R}P^1$

(Ex: check this!)

(e) Replace \mathbb{R} by $\mathbb{C} \leadsto$ Complex Projective Space $\mathbb{C}P^n$
(dim = $2n$)

Defⁿ: M is orientable if \exists atlas $\{(U_i, \phi_i)\}_{i \in I}$ s.t.
all transition maps are orientation-preserving
[i.e. $\det(d(\phi_j \circ \phi_i^{-1})) > 0$].

Examples: \mathbb{S}^n is orientable BUT $\mathbb{R}P^n$ is NOT when n is even.

§ Smooth Maps between manifolds

Let M^m, N^n be smooth manifolds.

Defⁿ: A cts map $f: M \rightarrow N$ is **smooth**

if $\forall x \in M, \exists$ charts (U, ϕ) for $x \in M$
and chart (V, ψ) for $f(x) \in N$

s.t. $\psi \circ f \circ \phi^{-1}: \phi(U) \rightarrow \psi(V)$ is smooth.

i.e.

$$\begin{array}{ccc} M \supseteq \overset{x}{U} & \xrightarrow{f} & \overset{f(x)}{V} \subseteq N \\ \phi \downarrow & \curvearrowright & \downarrow \psi \\ \mathbb{R}^m \supseteq \phi(U) & \xrightarrow{\psi \circ f \circ \phi^{-1}} & \psi(V) \subseteq \mathbb{R}^n \end{array}$$

Example: $M^n \subseteq \mathbb{R}^{n+k}$ submfld and $F: \mathbb{R}^{n+k} \rightarrow \mathbb{R}$ smooth

$\Rightarrow F|_M: M \rightarrow \mathbb{R}$ is a smooth map between manifolds

Defⁿ: A smooth map $f: M \rightarrow N$ is called an **immersion at $p \in M$**

if \exists charts (U, ϕ) for $M, (V, \psi)$ for N s.t.

$d(\psi \circ f \circ \phi^{-1})$ is 1-1 at $\phi(x)$.

Remark: **submersion / local diffeo.** if it is onto / bijective

Defⁿ: $f: M \rightarrow N$ **diffeomorphism** if f is bijective and
both f, f^{-1} are smooth.

Exercise: $\mathbb{C}P^1 \stackrel{\text{diffeo.}}{\cong} S^2$.

Locally (by IFT), in some local coord.,

immersion: $f(x_1, \dots, x_m) = (x_1, \dots, x_m, 0, \dots, 0)$
($m \leq n$)

Submersion: $f(x_1, \dots, x_m) = (x_1, \dots, x_n)$
($m \geq n$)

Defⁿ: $f: M \rightarrow N$ embedding

iff f is an immersion; and $f: M \rightarrow f(M)$ homeomorphism

Example: $M = (0, 1)$, $N = \mathbb{R}^2$; $f: (0, 1) \rightarrow \mathbb{R}^2$

